

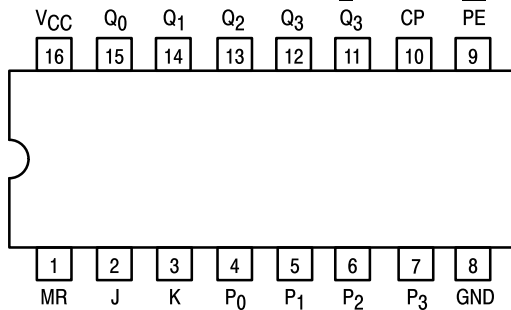


# UNIVERSAL 4-BIT SHIFT REGISTER

The SN54/74LS195A is a high speed 4-Bit Shift Register offering typical shift frequencies of 39 MHz. It is useful for a wide variety of register and counting applications. It utilizes the Schottky diode clamped process to achieve high speeds and is fully compatible with all Motorola TTL products.

- Typical Shift Right Frequency of 39 MHz
- Asynchronous Master Reset
- J, K Inputs to First Stage
- Fully Synchronous Serial or Parallel Data Transfers
- Input Clamp Diodes Limit High Speed Termination Effects

### CONNECTION DIAGRAM DIP (TOP VIEW)



NOTE:  
The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

### PIN NAMES

PE	Parallel Enable (Active LOW) Input
P <sub>0</sub> - P <sub>3</sub>	Parallel Data Inputs
J	First Stage J (Active HIGH) Input
K	First Stage K (Active LOW) Input
CP	Clock (Active HIGH Going Edge) Input
MR	Master Reset (Active LOW) Input
Q <sub>0</sub> - Q <sub>3</sub>	Parallel Outputs (Note b)
Q <sub>3</sub>	Complementary Last Stage Output (Note b)

### LOADING (Note a)

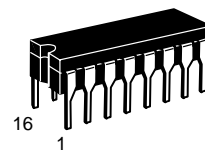
	HIGH	LOW
PE	0.5 U.L.	0.25 U.L.
P <sub>0</sub> - P <sub>3</sub>	0.5 U.L.	0.25 U.L.
J	0.5 U.L.	0.25 U.L.
K	0.5 U.L.	0.25 U.L.
CP	0.5 U.L.	0.25 U.L.
MR	0.5 U.L.	0.25 U.L.
Q <sub>0</sub> - Q <sub>3</sub>	10 U.L.	5 (2.5) U.L.
Q <sub>3</sub>	10 U.L.	5 (2.5) U.L.

### NOTES:

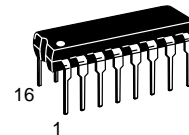
- a. 1 TTL Unit Load (U.L.) = 40  $\mu$ A HIGH/1.6 mA LOW.  
 b. The Output LOW drive factor is 2.5 U.L. for Military (54) and 5 U.L. for Commercial (74) Temperature Ranges.

## SN54/74LS195A

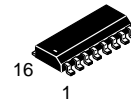
UNIVERSAL 4-BIT  
SHIFT REGISTER  
LOW POWER SCHOTTKY



J SUFFIX  
CERAMIC  
CASE 620-09



N SUFFIX  
PLASTIC  
CASE 648-08

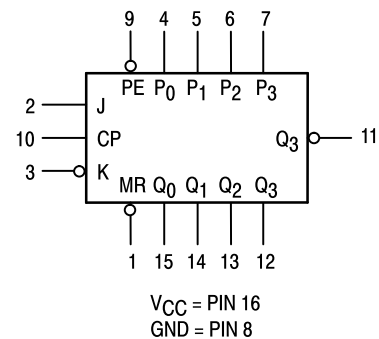


D SUFFIX  
SOIC  
CASE 751B-03

### ORDERING INFORMATION

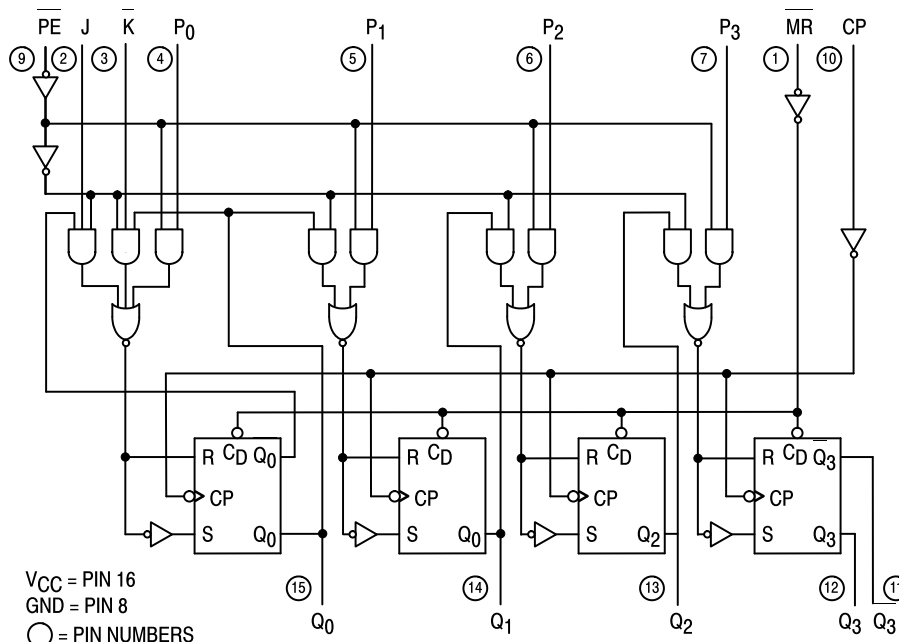
SN54LSXXXJ	Ceramic
SN74LSXXXN	Plastic
SN74LSXXXD	SOIC

### LOGIC SYMBOL



# SN54/74LS195A

## LOGIC DIAGRAM



## FUNCTIONAL DESCRIPTION

The Logic Diagram and Truth Table indicate the functional characteristics of the LS195A 4-Bit Shift Register. The device is useful in a wide variety of shifting, counting and storage applications. It performs serial, parallel, serial to parallel, or parallel to serial data transfers at very high speeds.

The LS195A has two primary modes of operation, shift right ( $Q_0 \rightarrow Q_1$ ) and parallel load which are controlled by the state of the Parallel Enable (PE) input. When the PE input is HIGH, serial data enters the first flip-flop  $Q_0$  via the J and K inputs and is shifted one bit in the direction  $Q_0 \rightarrow Q_1 \rightarrow Q_2 \rightarrow Q_3$  following each LOW to HIGH clock transition. The JK inputs provide the flexibility of the JK type input for special applications, and the simple D type input for general applications by tying the two

pins together. When the  $\overline{MR}$  input is LOW, the LS195A appears as four common clocked D flip-flops. The data on the parallel inputs  $P_0, P_1, P_2, P_3$  is transferred to the respective  $Q_0, Q_1, Q_2, Q_3$  outputs following the LOW to HIGH clock transition. Shift left operations ( $Q_3 \leftarrow Q_2$ ) can be achieved by tying the  $Q_n$  Outputs to the  $P_{n-1}$  inputs and holding the PE input LOW.

All serial and parallel data transfers are synchronous, occurring after each LOW to HIGH clock transition. Since the LS195A utilizes edge-triggering, there is no restriction on the activity of the J, K,  $P_n$  and PE inputs for logic operation — except for the set-up and release time requirements.

A LOW on the asynchronous Master Reset (MR) input sets all Q outputs LOW, independent of any other input condition.

MODE SELECT — TRUTH TABLE

OPERATING MODES	INPUTS					OUTPUTS				
	MR	PE	J	K	$P_n$	$Q_0$	$Q_1$	$Q_2$	$Q_3$	$Q_3$
Asynchronous Reset	L	X	X	X	X	L	L	L	L	H
Shift, Set First Stage	H	h	h	h	X	H	$q_0$	$q_1$	$q_2$	$q_2$
Shift, Reset First	H	h	l	l	X	$\underline{L}$	$q_0$	$q_1$	$q_2$	$q_2$
Shift, Toggle First Stage	H	h	h	l	X	$q_0$	$q_0$	$q_1$	$q_2$	$q_2$
Shift, Retain First Stage	H	h	l	h	X	$q_0$	$q_0$	$q_1$	$q_2$	$q_2$
Parallel Load	H	l	X	X	$p_n$	$p_0$	$p_1$	$p_2$	$p_3$	$p_3$

L = LOW voltage levels

H = HIGH voltage levels

X = Don't Care

l = LOW voltage level one set-up time prior to the LOW to HIGH clock transition.

h = HIGH voltage level one set-up time prior to the LOW to HIGH clock transition.

$p_n$  ( $q_n$ ) = Lower case letters indicate the state of the referenced input (or output) one set-up time prior to the LOW to HIGH clock transition.

# SN54/74LS195A

## GUARANTEED OPERATING RANGES

Symbol	Parameter		Min	Typ	Max	Unit
V <sub>CC</sub>	Supply Voltage	54 74	4.5 4.75	5.0 5.0	5.5 5.25	V
T <sub>A</sub>	Operating Ambient Temperature Range	54 74	-55 0	25 25	125 70	°C
I <sub>OH</sub>	Output Current — High	54, 74			-0.4	mA
I <sub>OL</sub>	Output Current — Low	54 74			4.0 8.0	mA

## DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

Symbol	Parameter	Limits			Unit	Test Conditions	
		Min	Typ	Max			
V <sub>IH</sub>	Input HIGH Voltage	2.0			V	Guaranteed Input HIGH Voltage for All Inputs	
V <sub>IL</sub>	Input LOW Voltage	54		0.7	V	Guaranteed Input LOW Voltage for All Inputs	
		74		0.8			
V <sub>IK</sub>	Input Clamp Diode Voltage		-0.65	-1.5	V	V <sub>CC</sub> = MIN, I <sub>IN</sub> = -18 mA	
V <sub>OH</sub>	Output HIGH Voltage	54	2.5	3.5	V	V <sub>CC</sub> = MIN, I <sub>OH</sub> = MAX, V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> per Truth Table	
		74	2.7	3.5	V		
V <sub>OL</sub>	Output LOW Voltage	54, 74		0.25	0.4	I <sub>OL</sub> = 4.0 mA	V <sub>CC</sub> = V <sub>CC</sub> MIN, V <sub>IN</sub> = V <sub>IL</sub> or V <sub>IH</sub> per Truth Table
		74		0.35	0.5	I <sub>OL</sub> = 8.0 mA	
I <sub>IH</sub>	Input HIGH Current			20	μA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7 V	
				0.1	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 7.0 V	
I <sub>IL</sub>	Input LOW Current			-0.4	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 0.4 V	
I <sub>OS</sub>	Short Circuit Current (Note 1)	-20		-100	mA	V <sub>CC</sub> = MAX	
I <sub>CC</sub>	Power Supply Current			21	mA	V <sub>CC</sub> = MAX	

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.

## AC CHARACTERISTICS (T<sub>A</sub> = 25°C)

Symbol	Parameter	Limits			Unit	Test Conditions
		Min	Typ	Max		
f <sub>MAX</sub>	Maximum Clock Frequency	30	39		MHz	V <sub>CC</sub> = 5.0 V C <sub>L</sub> = 15 pF
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay, Clock to Output		14 17	22 26	ns	
t <sub>PHL</sub>	Propagation Delay, MR to Output		19	30	ns	

## AC SETUP REQUIREMENTS (T<sub>A</sub> = 25°C)

Symbol	Parameter	Limits			Unit	Test Conditions
		Min	Typ	Max		
t <sub>W</sub>	CP Clock Pulse Width	16			ns	V <sub>CC</sub> = 5.0 V
t <sub>W</sub>	MR Pulse Width	12			ns	
t <sub>S</sub>	PE Setup Time	25			ns	
t <sub>S</sub>	Data Setup Time	15			ns	
t <sub>rec</sub>	Recovery Time	25			ns	
t <sub>rel</sub>	PE Release Time			10	ns	
t <sub>H</sub>	Data Hold Time	0			ns	

# SN54/74LS195A

## DEFINITIONS OF TERMS

**SETUP TIME ( $t_s$ )** — is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW to HIGH in order to be recognized and transferred to the outputs.

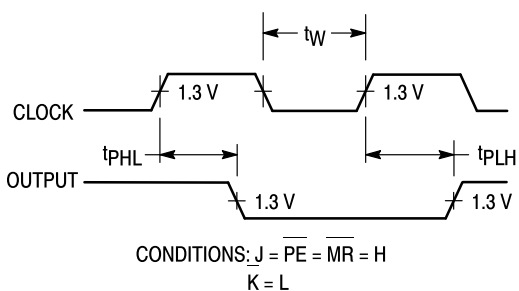
**HOLD TIME ( $t_h$ )** — is defined as the minimum time following the clock transition from LOW to HIGH that the logic level must be maintained at the input in order to ensure continued

recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from LOW to HIGH and still be recognized.

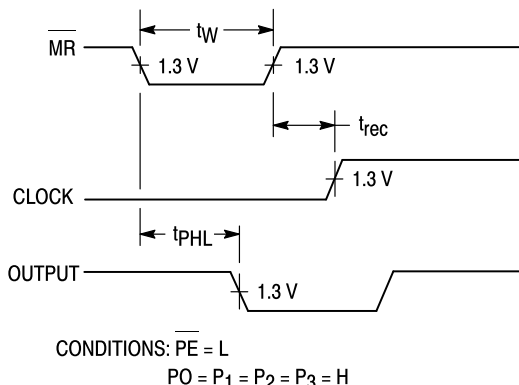
**RECOVERY TIME ( $t_{rec}$ )** — is defined as the minimum time required between the end of the reset pulse and the clock transition from LOW to HIGH in order to recognize and transfer HIGH Data to the Q outputs.

## AC WAVEFORMS

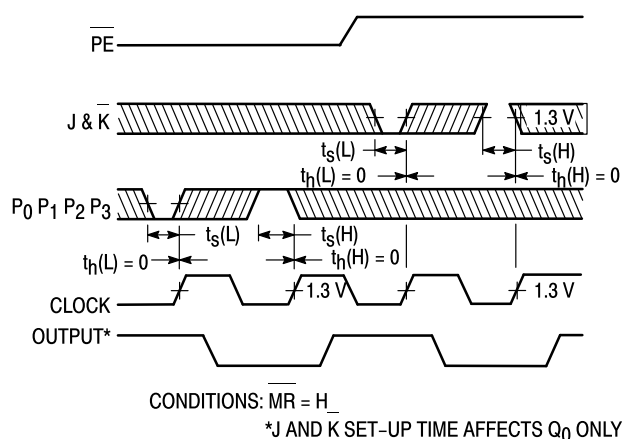
The shaded areas indicate when the input is permitted to change for predictable output performance.



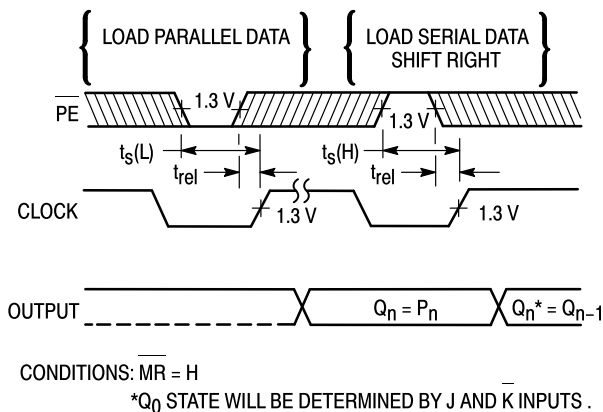
**Figure 1. Clock to Output Delays and Clock Pulse Width**



**Figure 2. Master Reset Pulse Width, Master Reset to Output Delay and Master Reset to Clock Recovery Time**

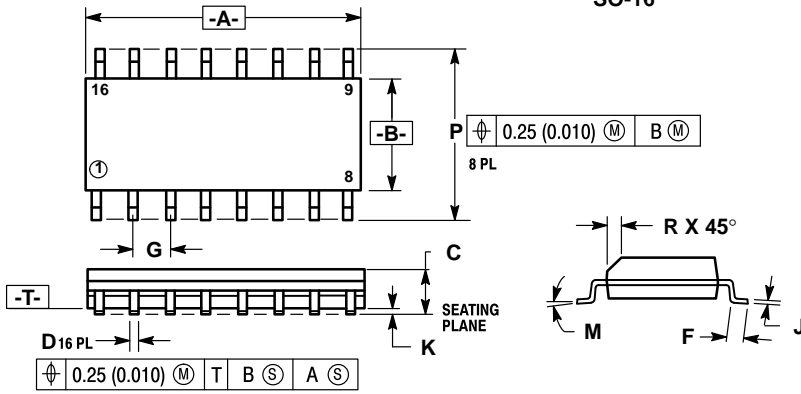


**Figure 3. Setup ( $t_s$ ) and Hold ( $t_h$ ) Time for Serial Data (J & K) and Parallel Data ( $P_0, P_1, P_2, P_3$ )**



**Figure 4. Setup ( $t_s$ ) and Hold ( $t_h$ ) Time for  $\overline{PE}$  Input**

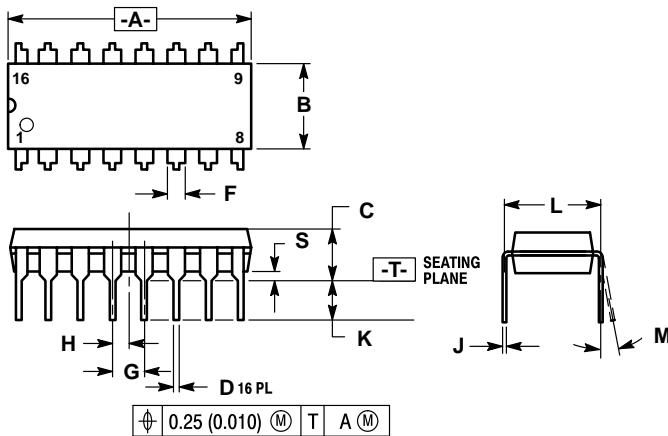
**Case 751B-03 D Suffix  
16-Pin Plastic  
SO-16**



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: MILLIMETER.
  3. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
  4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
  5. 751B-01 IS OBSOLETE, NEW STANDARD 751B-03.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9.80	10.00	0.386	0.393
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

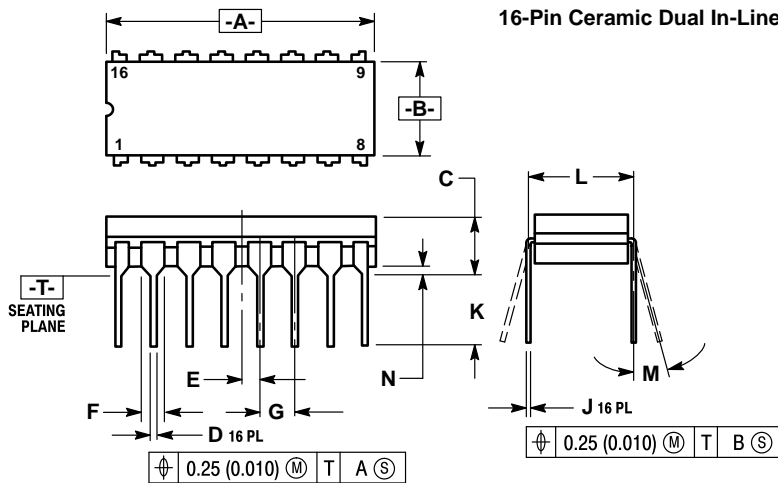
**Case 648-08 N Suffix  
16-Pin Plastic**



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION "L" TO CENTER OF LEADS WHEN FORMED PARALLEL.
  4. DIMENSION "B" DOES NOT INCLUDE MOLD FLASH.
  5. ROUNDED CORNERS OPTIONAL.
  6. 648-01 THRU -07 OBSOLETE, NEW STANDARD 648-08.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	18.80	19.55	0.740	0.770
B	6.35	6.85	0.250	0.270
C	3.69	4.44	0.145	0.175
D	0.39	0.53	0.015	0.021
F	1.02	1.77	0.040	0.070
G	2.54 BSC		0.100 BSC	
H	1.27 BSC		0.050 BSC	
J	0.21	0.38	0.008	0.015
K	2.80	3.30	0.110	0.130
L	7.50	7.74	0.295	0.305
M	0°	10°	0°	10°
S	0.51	1.01	0.020	0.040

**Case 620-09 J Suffix  
16-Pin Ceramic Dual In-Line**



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
  4. DIM F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY.
  5. 620-01 THRU -08 OBSOLETE, NEW STANDARD 620-09.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	19.05	19.55	0.750	0.770
B	6.10	7.36	0.240	0.290
C	—	4.19	—	0.165
D	0.39	0.53	0.015	0.021
E	1.27 BSC		0.050 BSC	
F	1.40	1.77	0.055	0.070
G	2.54 BSC		0.100 BSC	
J	0.23	0.27	0.009	0.011
K	—	5.08	—	0.200
L	7.62 BSC		0.300 BSC	
M	0°	15°	0°	15°
N	0.39	0.88	0.015	0.035

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters can and do vary in different applications. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights nor the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola and <sup>TM</sup> are registered trademarks of Motorola, Inc. Motorola, Inc. is an Equal Opportunity/Affirmative Action Employer.

**Literature Distribution Centers:**

USA: Motorola Literature Distribution; P.O. Box 20912; Phoenix, Arizona 85036.

EUROPE: Motorola Ltd.; European Literature Centre; 88 Tanners Drive, Blakelands, Milton Keynes, MK14 5BP, England.

JAPAN: Nippon Motorola Ltd.; 4-32-1, Nishi-Gotanda, Shinagawa-ku, Tokyo 141, Japan.

ASIA PACIFIC: Motorola Semiconductors H.K. Ltd.; Silicon Harbour Center, No. 2 Dai King Street, Tai Po Industrial Estate, Tai Po, N.T., Hong Kong.

