# RENESAS HD74ALVCH162831

1-bit 4-bit Address Register / Driver with 3-state Outputs

REJ03D0039-0200Z (Previous ADE-205-195(Z)) Rev.2.00 Oct.02.2003

#### Description

This 1-bit to 4-bit address register / driver is designed for 2.3 V to 3.6 V V<sub>CC</sub> operation. The device is ideal for use in applications in which a single address bus is driving four separate memory locations. The HD74ALVCH162831 can be used as a buffer or a register, depending on the logic level of the select (SEL) input. When SEL is logic high, the device is in the buffer mode. The outputs follow the inputs and are controlled by the two output enable ( $\overline{OE}$ ) controls. Each  $\overline{OE}$  controls two groups of nine outputs. When SEL is logic low, the device is in the register mode. The register is an edge triggered D-type flip flop. On the positive transition of the clock (CLK) input, data set up at the A inputs is stored in the internal registers.  $\overline{OE}$  controls operate the same as in buffer mode. When  $\overline{OE}$  is logic low, the outputs are in a normal logic state (high or low logic level). When  $\overline{OE}$  is logic high, the outputs are in the high impedance state. To ensure the high impedance state during power up or power down,  $\overline{OE}$  should be tied to V<sub>CC</sub> through a pullup register; the minimum value of the register is determined by the current sinking capability of the driver. SEL and  $\overline{OE}$  do not affect the internal operation of the flip flops. Old data can be retained or new data can be entered while the outputs are in the high impedance state. Active bus hold circuitry is provided to hold unused or floating data inputs at a valid logic level. All outputs, which are designed to sink up to 12 mA, include 26  $\Omega$  resistors to reduce overshoot and undershoot.

### Features

- $V_{CC} = 2.3 \text{ V}$  to 3.6 V
- Typical V<sub>OL</sub> ground bounce < 0.8 V (@V<sub>CC</sub> = 3.3 V, Ta = 25°C)
- High output current  $\pm 12 \text{ mA} (@V_{CC} = 3.0 \text{ V})$
- Bus hold on data inputs eliminates the need of
- Bus hold on data inputs eliminates the need of
- All outputs have equivalent 26  $\Omega$  series resistors, so no external resistors are required.



#### **Function Table**

Inputs	Output Y			
ŌĒ	SEL	CLK	А	
Н	Х	Х	Х	Z
L	Н	Х	L	L
L	Н	Х	Н	Н
L	L	Ŷ	L	L
L	L	$\uparrow$	Н	Н

H : High level

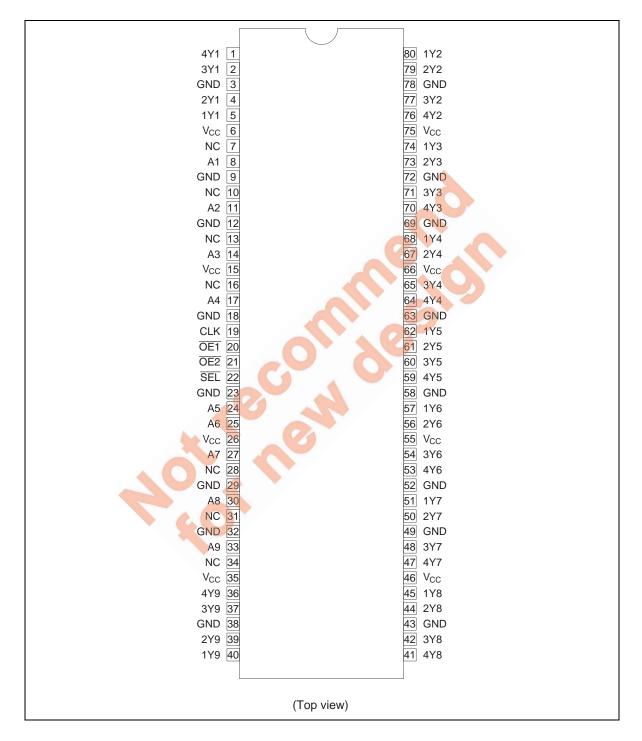
L : Low level X : Immaterial

Z : High impedance

 $\uparrow$  : Low to high transition

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#### **Pin Arrangement**





Item	Symbol	Ratings	Unit	Conditions
Supply voltage	V <sub>cc</sub>	–0.5 to 4.6	V	
Input voltage *1	VI	–0.5 to 4.6	V	
Output voltage *1, 2	Vo	–0.5 to V <sub>CC</sub> +0.5	V	
Input clamp current	I <sub>IK</sub>	-50	mA	V <sub>1</sub> < 0
Output clamp current	I <sub>OK</sub>	±50	mA	$V_{\rm O}$ < 0 or $V_{\rm O}$ > $V_{\rm CC}$
Continuous output current	lo	±50	mA	$V_{O} = 0$ to $V_{CC}$
V <sub>CC</sub> , GND current / pin	$I_{CC}$ or $I_{GND}$	±100	mA	
Maximum power dissipation at Ta = 55°C (in still air) $^{*3}$	P <sub>T</sub>	1	W	TVSOP
Storage temperature	T <sub>stg</sub>	-65 to 150	°C	

#### **Absolute Maximum Ratings**

Notes: Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

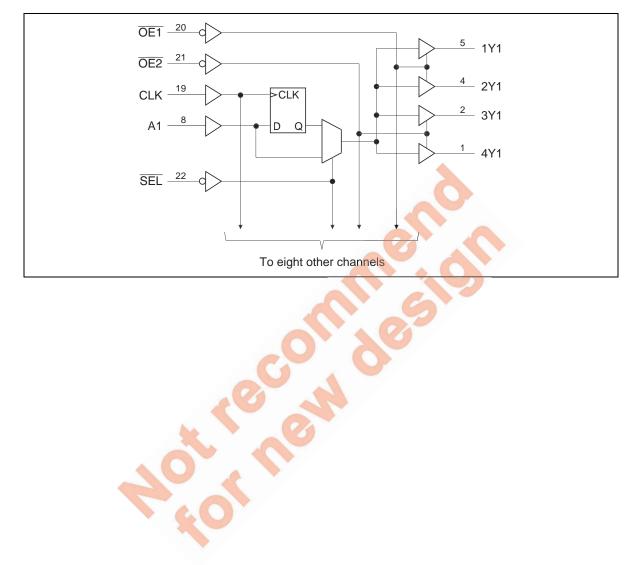
- 1. The input and output negative voltage ratings may be exceeded if the input and output clamp current ratings are observed.
- 2. This value is limited to 4.6 V maximum.
- 3. The maximum package power dissipation is calculated using a junction temperature of 150°C and a board trace length of 750 mils.

### **Recommended Operating Conditions**

Item	Symbol	Min	Max	Unit	Conditions
Supply voltage	V <sub>cc</sub>	2.3	3.6	V	
Input voltage	VI	0	Vcc	V	
Output voltage	Vo	0	V <sub>CC</sub>	V	
High level output current	Іон	_	-6	mA	$V_{CC}$ = 2.3 V
		_	-8		V <sub>CC</sub> = 2.7 V
		_	-12		V <sub>CC</sub> = 3.0 V
Low level output current	I <sub>OL</sub>	_	6	mA	V <sub>CC</sub> = 2.3 V
		_	8		V <sub>CC</sub> = 2.7 V
		_	12		V <sub>CC</sub> = 3.0 V
Input transition rise or fall rat	e $\Delta t / \Delta v$	0	10	ns / V	
Operating temperature	Ta	-40	85	°C	

Note: Unused control inputs must be held high or low to prevent them from floating.

#### Logic Diagram





#### **Electrical Characteristics**

#### $(Ta = -40 \text{ to } 85^{\circ}C)$

Item	Symbol	V <sub>cc</sub> (V)	Min	Max	Unit	Test Conditions
Input voltage	V <sub>IH</sub>	2.3 to 2.7	1.7	_	V	
		2.7 to 3.6	2.0	_	_	
	V <sub>IL</sub>	2.3 to 2.7		0.7	_	
		2.7 to 3.6	_	0.8		
Output voltage	V <sub>OH</sub>	2.3 to 3.6	V <sub>CC</sub> -0.2	_	V	I <sub>OH</sub> = −100 μA
		2.3	1.9	_	_	I <sub>OH</sub> = -4 mA, V <sub>IH</sub> = 1.7 V
		2.3	1.7	_	-	l <sub>он</sub> = −6 mA, V <sub>IH</sub> = 1.7 V
		2.7	2.4	_		I <sub>OH</sub> = –6 mA, V <sub>IH</sub> = 2.0 V
		3.0	2.0	- /		$I_{OH} = -8 \text{ mA}, V_{IH} = 2.0 \text{ V}$
		3.0	2.0	-	0	I <sub>OH</sub> = -12 mA, V <sub>IH</sub> = 2.0 V
	V <sub>OL</sub>	2.3 to 3.6	- /	0.2		I <sub>OL</sub> = 100 μA
		2.3	-	0.4		$I_{OL} = 4 \text{ mA}, V_{IL} = 0.7 \text{ V}$
		2.3	-	0.55		$I_{OL} = 6 \text{ mA}, V_{IL} = 0.7 \text{ V}$
		3.0		0.55	5	$I_{OL} = 6 \text{ mA}, V_{IL} = 0.8 \text{ V}$
		2.7		0.6		$I_{OL} = 8 \text{ mA}, V_{IL} = 0.8 \text{ V}$
		3.0	- <	0.8		$I_{OL} = 12 \text{ mA}, V_{IL} = 0.8 \text{ V}$
Input current	I <sub>IN</sub>	3.6	70	±5	μΑ	$V_{IN} = V_{CC}$ or GND
	IIN (hold)	2.3	45	-	_	V <sub>IN</sub> = 0.7 V
		2.3	-45	_	_	V <sub>IN</sub> = 1.7 V
		3.0	75	_	_	V <sub>IN</sub> = 0.8 V
		3.0	-75	_	_	V <sub>IN</sub> = 2.0 V
		3.6	_	±500	_	$V_{IN} = 0$ to 3.6 V <sup>*1</sup>
Off state output current	loz	3.6	_	±10	μΑ	$V_{OUT} = V_{CC}$ or GND
Quiescent supply current	lcc	3.6	_	40	μΑ	$V_{IN} = V_{CC}$ or GND
	Δlcc	3.0 to 3.6		750	μΑ	$V_{IN}$ = one input at (V <sub>CC</sub> -0.6) V, other inputs at V <sub>CC</sub> or GND

Note: 1. This is the bus hold maximum dynamic current required to switch the input from one state to another.

### **Switching Characteristics**

#### $(Ta = -40 \text{ to } 85^{\circ}\text{C})$

Item	Symbol	V <sub>cc</sub> (V)	Min	Тур	Max	Unit	FROM (Input)	TO (Output)
Maximum clock frequenc	f <sub>max</sub>	2.5±0.2	150			MHz		
		2.7	150		_			
		3.3±0.3	150			_		
Propagation delay time	t <sub>PLH</sub>	2.5±0.2	1.1		4.7	ns	А	Y
	t <sub>PHL</sub>	2.7	—		4.8	_		
		3.3±0.3	1.5		4.3			
		2.5±0.2	1.0		5.3		CLK	Y
		2.7	—		5.3			
		3.3±0.3	1.4		4.7		$\sim$	
		2.5±0.2	1.1	-	6.0		SEL	Y
		2.7	-		6.2		5	
		3.3±0.3	1.5	-	4.8			
Output enable time	t <sub>ZH</sub>	2.5±0.2	1.0	-	5.9	ns	ŌĒ	Y
	t <sub>ZL</sub>	2.7		-	5.9			
		3.3±0.3	1.1		5.1	_		
Output disable time	t <sub>HZ</sub>	2.5±0.2	1.4	-	6.3	ns	ŌĒ	Y
	t <sub>LZ</sub>	2.7	-	1	5.4			
		3.3±0.3	1.6	_	5.1			
Setup time	t <sub>su</sub>	2.5 <u>±0.2</u>	2.0	_	_	ns		
		2.7	2.0	_	_			
		3.3±0.3	1.6	_	_			
Hold time	th	2.5±0.2	0.7	_	_	ns		
	X	2.7	0.5	_	_			
		3.3±0.3	1.1		_			
Pulse width	t <sub>w</sub>	2.5±0.2	3.3		_	ns		
		2.7	3.3					
		3.3±0.3	3.3					
Input capacitance	C <sub>IN</sub>	3.3	—	4.5		pF	Control in	outs
		3.3	—	5.0			Data input	S
Output capacitance	Co	3.3	_	7.5	_	рF		

#### **Switching Characteristics**

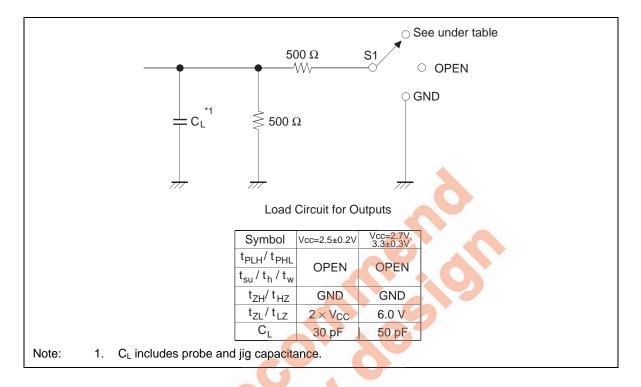
#### $(Ta = 0 \text{ to } 65^{\circ}C)$

Item	Symbol V <sub>cc</sub> (V) Min	Тур	Мах	Unit	FROM (Input)	TO (Output)
Propagation delay time	t <sub>PLH</sub> , t <sub>PHL</sub> 3.3±0.15 1.9	_	4.5	ns	CLK	Y



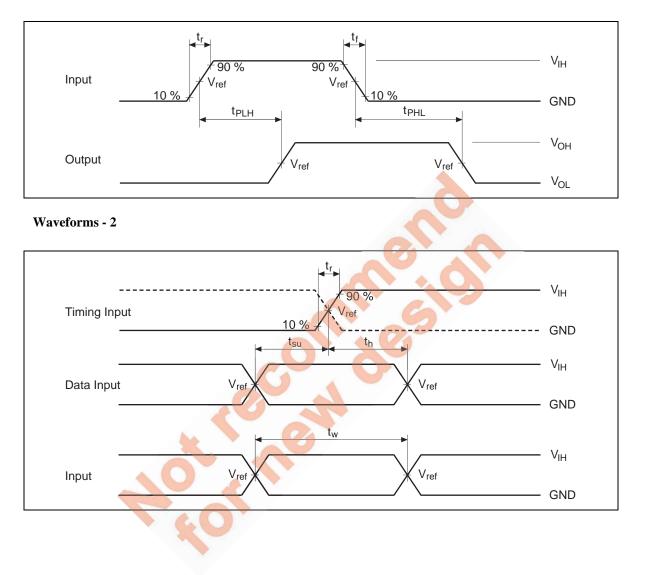


#### **Test Circuit**



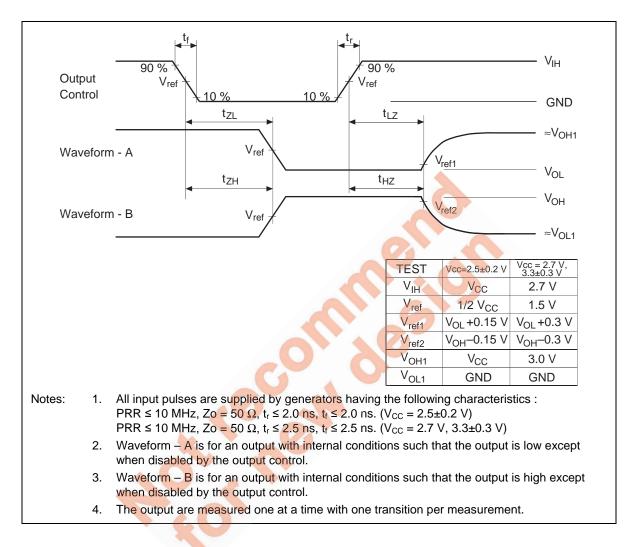


#### Waveforms - 1



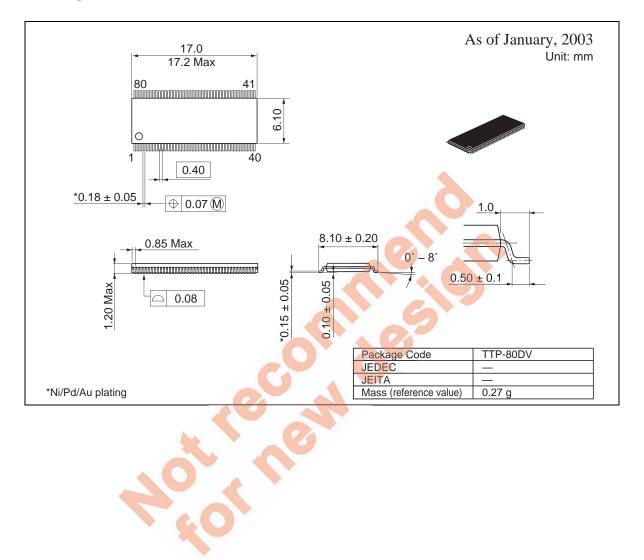


#### Waveforms - 3





### **Package Dimensions**





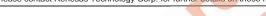
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