4-bit Parallel-Access Shift Register

HITACHI

Description

This shift register features parallel inputs, parallel outputs, $J-\overline{K}$ serial inputs, Shift/Load control input, and a direct overriding clear. This shift register can operate in two modes: Parallel load; Shift from Q_0 towards Q_3 .

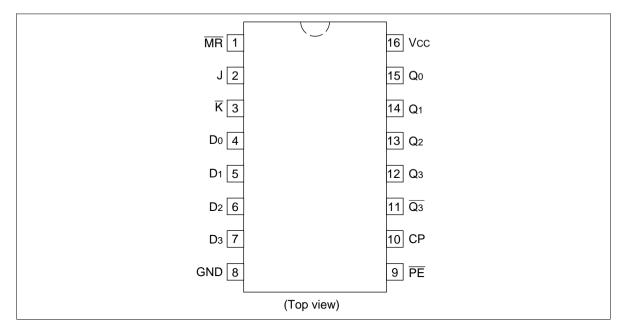
Parallel loading is accomplished by applying the four bits of data, and taking the \overline{PE} Input low. The data is loaded into the associated flip-flops and appears at the outputs after the positive transition of the CP input. During parallel loading, serial data flow is inhibited. Serial shifting occurs synchronously when the \overline{PE} input is high. Serial data for this mode is entered at the J- \overline{K} inputs. These inputs allow the first stage to perform as a J- \overline{K} or toggle flip-flop as shown in the function table.

Features

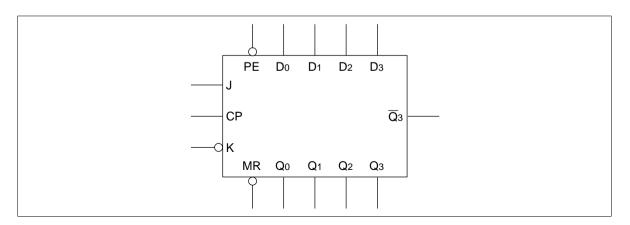
- Shift Right and Parallel Load Capability
- J-K (D-Type) Inputs to First Stage
- Complement Output from Last Stage
- Asynchronous Master Reset
- Outputs Source/Sink 24 mA



Pin Arrangement



Logic Symbol



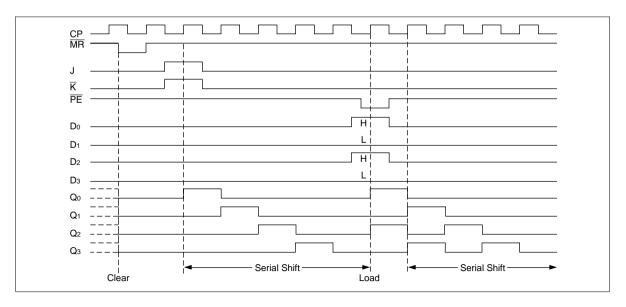
Pin Names

CP Clock Pulse Input (Active Rising Edge)

 $\begin{array}{lll} D_0 \ to \ D_3 & Parallel \ Data \ Inputs \\ \hline \overline{PE} & Parallel \ Enable \ Input \\ \hline \overline{MR} & Asynchronous \ Master \ Reset \\ J, \ \overline{K} & J-\overline{K} \ or \ D \ Type \ Serial \ Inputs \end{array}$

 Q_0 to Q_3 , \overline{Q}_3 Outputs

Timing Diagram



Mode Select-Function Table

	Input	ts					Outp	uts			
Operating Modes	MR	СР	PE	J	K	D _n	$\mathbf{Q}_{\scriptscriptstyle{0}}$	Q ₁	Q_2	Q_3	$\overline{\mathbf{Q}}_{\scriptscriptstyle 3}$
Asynchronous Reset	L	Χ	Х	Χ	Х	Х	L	L	L	L	Н
Shift, Set First Stage	Н	\int	Н	Н	Н	Х	Н	q_{0}	$q_{\scriptscriptstyle 1}$	q_2	$\overline{\overline{q}}_{\scriptscriptstyle 2}$
Shift, Reset First Stage	Н		Н	L	L	Х	L	$\mathbf{q}_{\scriptscriptstyle 0}$	$q_{\scriptscriptstyle 1}$	q_2	$\overline{\overline{q}}_{\scriptscriptstyle 2}$
Shift, Toggle First Stage	Н	\int	Н	Н	L	Χ	$\overline{q}_{\scriptscriptstyle 0}$	\mathbf{q}_{o}	$q_{\scriptscriptstyle 1}$	q_2	$\overline{q}_{\scriptscriptstyle 2}$
Shift, Retain First Stage	Н	\int	Н	L	Н	Х	q_{0}	q_{0}	$q_{\scriptscriptstyle 1}$	q_2	$\overline{\overline{q}}_{\scriptscriptstyle 2}$
Parallel Load	Н		L	Х	Х	d _n	d_0	d ₁	d ₂	d ₃	\overline{d}_3

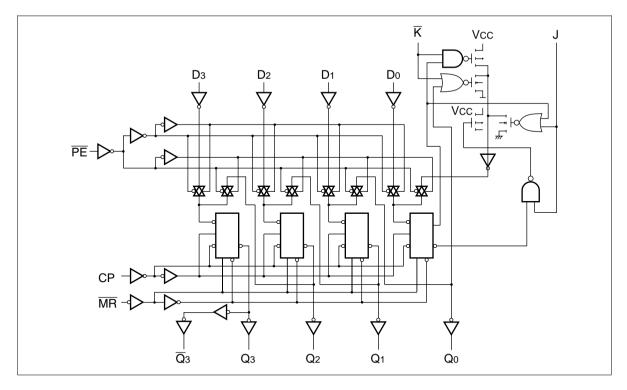
H: HIGH Voltage Level

L : LOW Voltage Level X : Immaterial

Lower case letters indicate the state of the referenced input (or output) one setup time prior to the LOW-to-HIGH transition.

 \int : LOW-to-HIGH clock transition.

Logic Diagram



DC Characteristics (unless otherwise specified)

Item	Symbol	Max	Unit	Condition
Maximum quiescent supply current	I _{cc}	80	μΑ	$V_{IN} = V_{CC}$ or ground, $V_{CC} = 5.5 \text{ V}$, Ta = Worst case
Maximum quiescent supply current	I _{cc}	8.0	μΑ	$V_{IN} = V_{CC}$ or ground, $V_{CC} = 5.5 \text{ V}$, $Ta = 25^{\circ}\text{C}$

AC Characteristics: HD74AC195

			$Ta = +25^{\circ}C$ $C_{L} = 50 \text{ pF}$		Ta = -40° C to $+85^{\circ}$ C C _L = 50 pF			
Item	Symbol	V _{cc} (V)*1	Min	Тур	Max	Min	Max	Unit
Maximum clock	f_{max}	3.3	75	_	_	65	_	MHz
frequency		5.0	100	_	_	85	_	
Propagation delay	t _{PLH}	3.3	1.0	9.0	13.0	1.0	15.0	ns
CP to Q_n or \overline{Q}_3		5.0	1.0	5.5	10.0	1.0	11.5	
Propagation delay	t _{PHL}	3.3	1.0	9.0	13.0	1.0	15.0	ns
CP to Q_n or \overline{Q}_2		5.0	1.0	6.5	10.0	1.0	11.5	_
Propagation delay	t _{PLH}	3.3	1.0	7.5	10.5	1.0	12.0	ns
\overline{MR} to $\overline{Q}_{\scriptscriptstyle 2}$		5.0	1.0	5.5	8.0	1.0	9.5	_
Propagaion delay	t _{PHL}	3.3	1.0	6.0	9.0	1.0	10.5	ns
\overline{MR} to \overline{Q}_n		5.0	1.0	5.0	7.0	1.0	8.0	_

Note: 1. Voltage Range 3.3 is $3.3 \text{ V} \pm 0.3 \text{ V}$ Voltage Range 5.0 is $5.0 \text{ V} \pm 0.5 \text{ V}$

AC Operating Requirements: HD74AC195

			Ta = +25°C C _L = 50 pF		Ta = -40°C to +85°C C _L = 50 pF	
Item	Symbol	V _{cc} (V)*1	Тур	Guarantee	d Minimum	Unit
Setup time, HIGH or LOW	t _{su}	3.3	3.0	5.5	7.0	ns
J, \overline{K} or \overline{D}_n to CP		5.0	2.0	4.0	5.0	
Hold time, HIGH or LOW	t _h	3.3	-0.5	2.0	3.6	ns
J, \overline{K} or \overline{D}_n to CP		5.0	0.5	1.5	2.0	
Setup time, HIGH or LOW	t _{su}	3.3	3.5	5.0	7.0	ns
PE to CP		5.0	2.5	4.0	5.0	
Hold time, HIGH or LOW	t _h	3.3	-2.0	0.0	0.0	ns
PE to CP		5.0	-1.5	0.0	0.0	
Recovery time	t _{rec}	3.3	-1.5	0.5	0.5	ns
MR to CP		5.0	-1.0	0.5	0.5	
Pulse width	t _w	3.3	-3.0	5.5	7.0	ns
		5.0	-3.0	4.5	5.0	

Note: 1. Voltage Range 3.3 is $3.3 \text{ V} \pm 0.3 \text{ V}$ Voltage Range 5.0 is $5.0 \text{ V} \pm 0.5 \text{ V}$

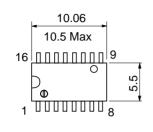
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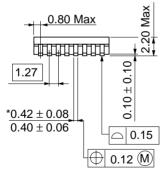
Capacitance

Item	Symbol	Тур	Unit	Condition
Input capacitance	C _{IN}	4.5	pF	$V_{cc} = 5.5 \text{ V}$
Power dissipation capacitance	C_{\scriptscriptstylePD}	125	pF	V _{cc} = 5.0 V

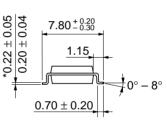
Unit: mm 19.20 20.00 Max 16 7.40 Max 6.30 1.3 1.11 Max 7.62 5.06 Max 2.54 Min 0.51 Min $0.25^{+0.13}_{-0.05}$ 0.48 ± 0.10 2.54 ± 0.25 $0^{\circ} - 15^{\circ}$ Hitachi Code DP-16 **JEDEC** Conforms EIAJ Conforms Weight (reference value) 1.07 g

Unit: mm





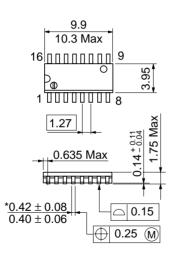


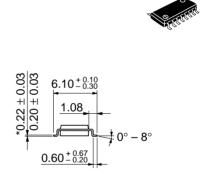


Hitachi Code	FP-16DA
JEDEC	
EIAJ	Conforms
Weight (reference value)	0.24 a

*Dimension including the plating thickness
Base material dimension

Unit: mm

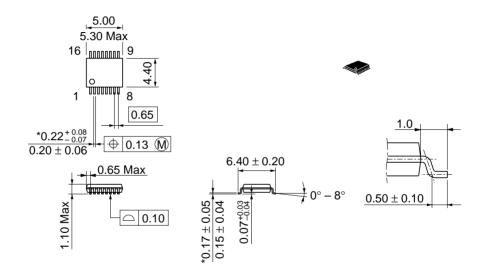




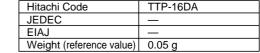
*Dimension including the plating thickness Base material dimension

Hitachi Code	FP-16DN
JEDEC	Conforms
EIAJ	Conforms
Weight (reference value)	0.15 g

Unit: mm



*Dimension including the plating thickness
Base material dimension



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