

# HA17524P/FP

## Switching Regulator Controller

# HITACHI

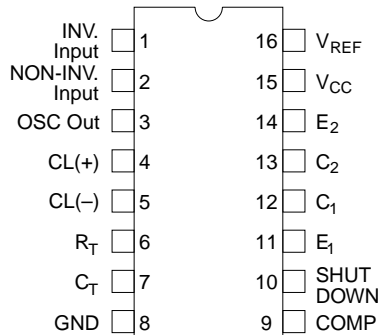
### Features

- Pulse width modulation (PWM)
- Wide oscillation frequency range: 450 kHz(typ)
- Low quiescent current: 5 mA typ
- Good line regulation (0.2% typ) and load regulation (0.4% typ)
- Independent output stages for 2 channels
- Wide external circuit applications including single-end and push-pull method
- Reference power source output stage and switching output stage include current limiting protection circuit.

### Ordering Information

| Type No.  | Package                            |
|-----------|------------------------------------|
| HA17524P  | 16 pin dual in line plastic(DP-16) |
| HA17524FP | 16 pin flat plastic (FP-16DA)      |

### Pin Arrangement



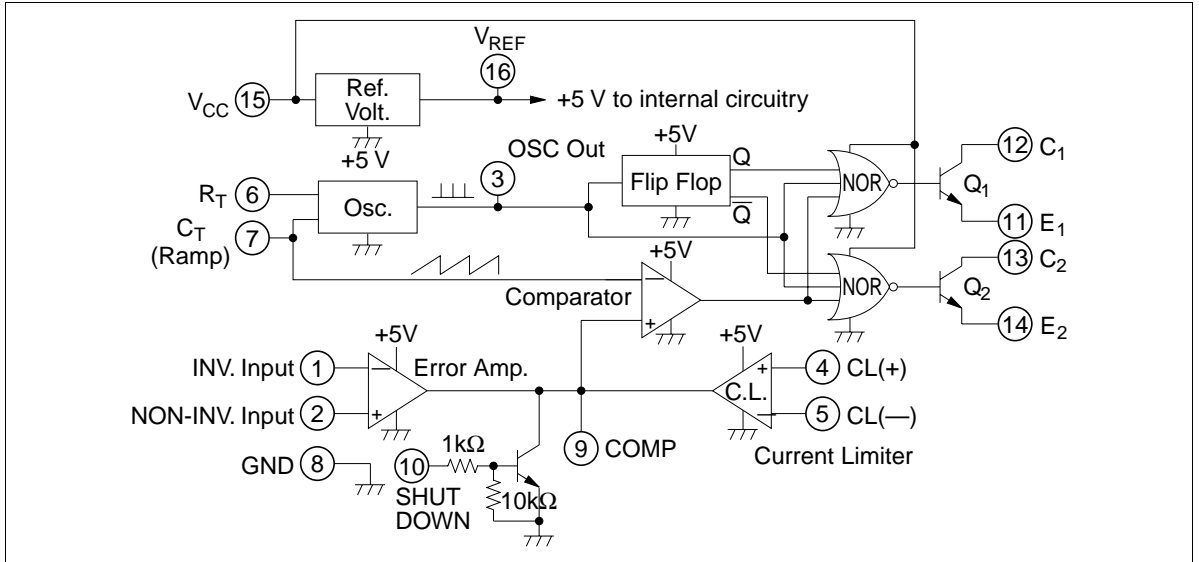
(Top View)

## Functional Description

### Principals of HA17524 Operation

The HA17524 switching regulator circuit, using pulse width modulation (PWM), is constructed as shown in figure 1.

Timing resistances  $R_T$  and timing capacitance  $C_T$  control the oscillation frequency.  $C_T$  is charged by a constant current generated by  $R_T$ . Ramp signals (saw-tooth waves) at the  $C_T$  terminal generated by this oscillator is available for reference input signal to comparator which control the pulse width.



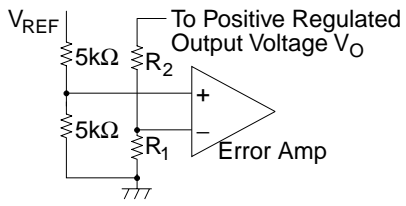
**Figure 1 HA17524 Block Diagram**

The reference voltage connects to the non-inverted or inverted input terminal of the error amplifier via resistance divider (figure 2).

The output voltage from the error amplifier is compared with the ramp signal capacitance  $C_T$  (figure 1). The comparator can provide a signal with modulated pulse width.

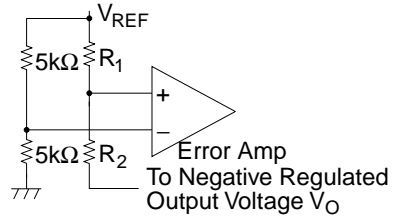
This signal, then, controls output transistors  $Q_1$  and  $Q_2$ , making an open loop to stabilize output voltage.

Outputs from the error amplifier, the current limiter, and the shut-down circuit are connected together at the comparator, so that an input signal from any one of these circuits can break the output stage.



(a) Forward Output Stabilizing Source

$$V_O = 2.5 \frac{R_1 + R_2}{R_1} \text{ (V)}$$



(b) Reverse Output Stabilizing Source

$$V_O = 5 - 2.5 \frac{R_1 + R_2}{R_1} \text{ (V)}$$

**Figure 2 Error Amplifier Biasing**

**Blocks Description**

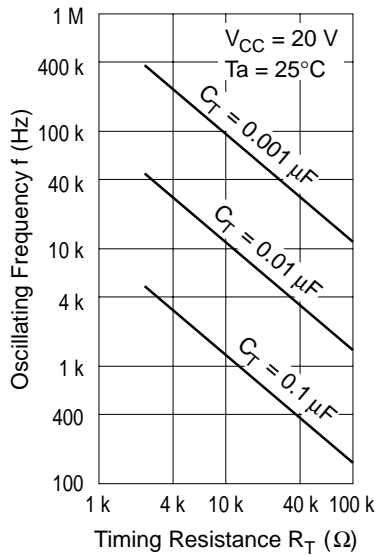
Oscillator: The oscillation frequency  $f$  is calculated from the following equations. Figure 3 shows one example.

$$f = 1.15 / (R_T \cdot C_T)$$

$$R_T = 1.8\text{k} \text{ to } 100\text{k } \Omega$$

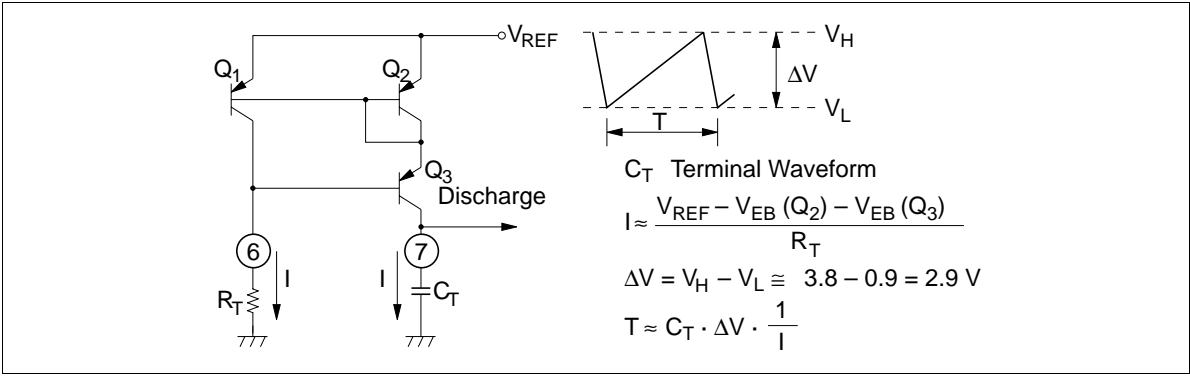
$$C_T = 0.001\mu \text{ to } 0.1\ \mu\text{F}$$

$$f = 140\text{ Hz} \text{ to } 500\text{ kHz}$$



**Figure 3 Oscillating Frequency vs Timing Resistance**

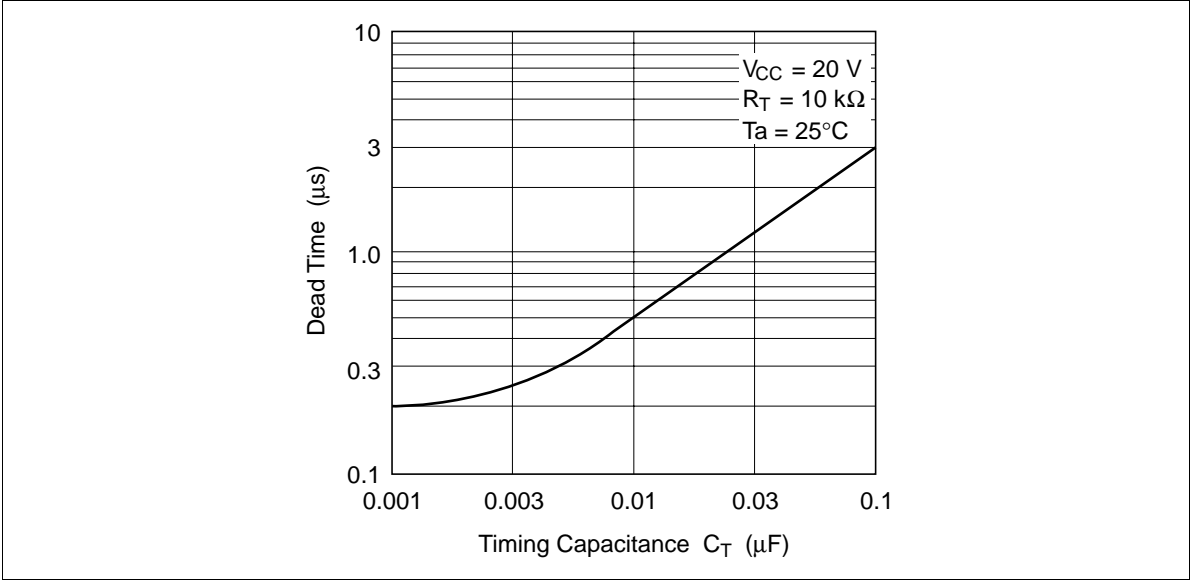
Then the ramp wave shown in figure 4 is available at pin 7,  $C_T$  terminal, since  $C_T$  is charged by the constant current  $I$  generated by  $R_T$ .



**Figure 4 Oscillating Circuit and  $C_T$  Terminal Waveform**

The oscillator output pulse signal is used as the flip flop clock pulse and as switching pulses for the output transistors, synchronous to the clock pulse.

The pulse-widths which can be controlled by the timing capacitor  $C_T$  as shown in figure 5, increases output dead time.



**Figure 5 Dead Time vs Timing Capacitance**

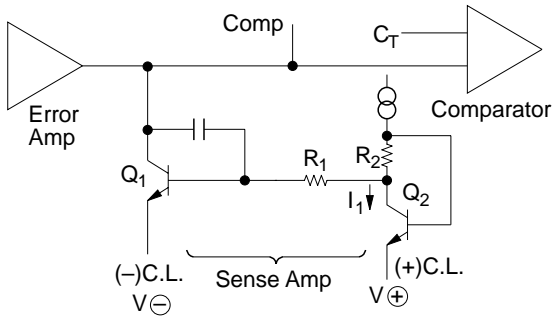
Reference Voltage: The built-in regulator (reference voltage:  $V_{REF} = 5 \pm 0.4 \text{ V}$ ) can be used as a reference power supply for the error amplifier, which determines output voltage ( $V_{OUT}$ ). It is also connected as a bias source for another circuits in IC.

**Error Amplifier:** Figure 2 shows error amplifier biasing, applied input voltage must be set within the range of common-mode input voltage (1.8 V to 3.4 V). Inserting a resistor and capacitor between phase compensation terminal (pin 9) and GND in series provides phase compensation.

**Current Limiter:** The sense amplifier threshold voltage ( $V_S$ ) for the current limiter is:

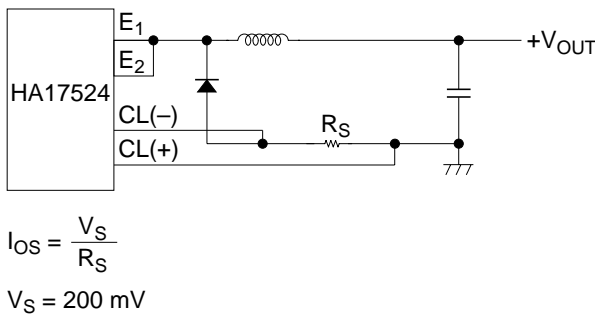
$$\begin{aligned} V_S &= V_{BE}(Q_1) + I_1 R_2 - V_{BE}(Q_2) \\ &= I_1 R_2 \\ &= 200 \text{ mV typ} \end{aligned}$$

At the current limiter sense amp shown in figure 6, when  $V^+ - V^- > 200 \text{ mV}$ ,  $Q_1$  turns on, phase compensation terminal becomes low and the output switching element is cut off.



**Figure 6 Current Limiter Sense Amplifier**

Figure 7 shows an example of detecting current limit. The input voltage range is  $-0.7 \text{ V}$  to  $+1.0 \text{ V}$ ; The current limit detection output is provided from GND line.



**Figure 7 Current Limit Detector Example Operating Waveforms**

Operating Waveforms

Figure 9 shows operating waveforms at every part, when stepdown voltage type chopper switching regulator (figure 8) is used. Operating condition are as follows:  $f = 20 \text{ kHz}$ ,  $V_{\text{OUT}} = 5 \text{ V}$ . At the output section, two channels are connected in parallel. Operating waveforms inside the IC are also shown.

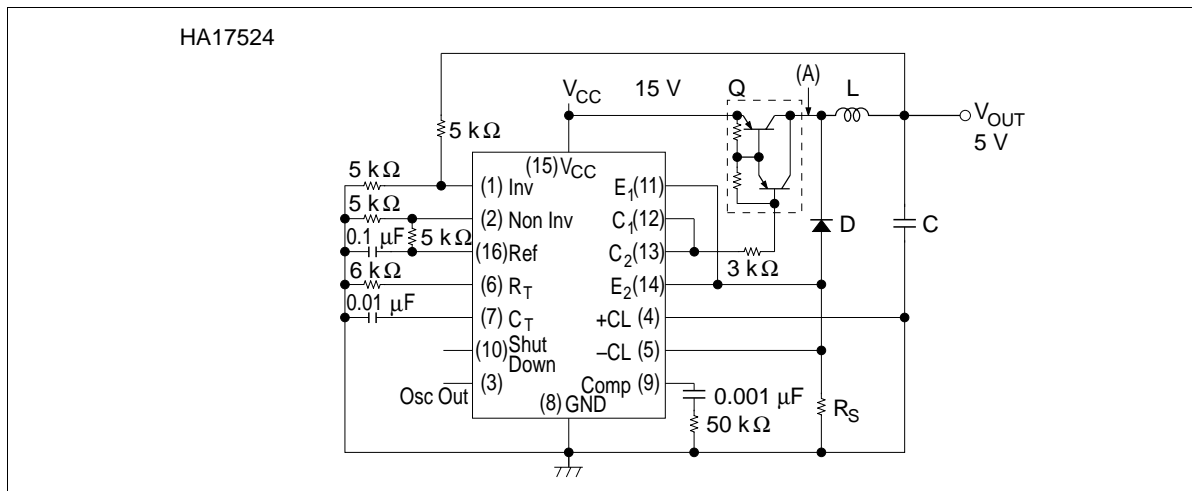


Figure 8 Stepdown Voltage Type Chopper Switching Regulator

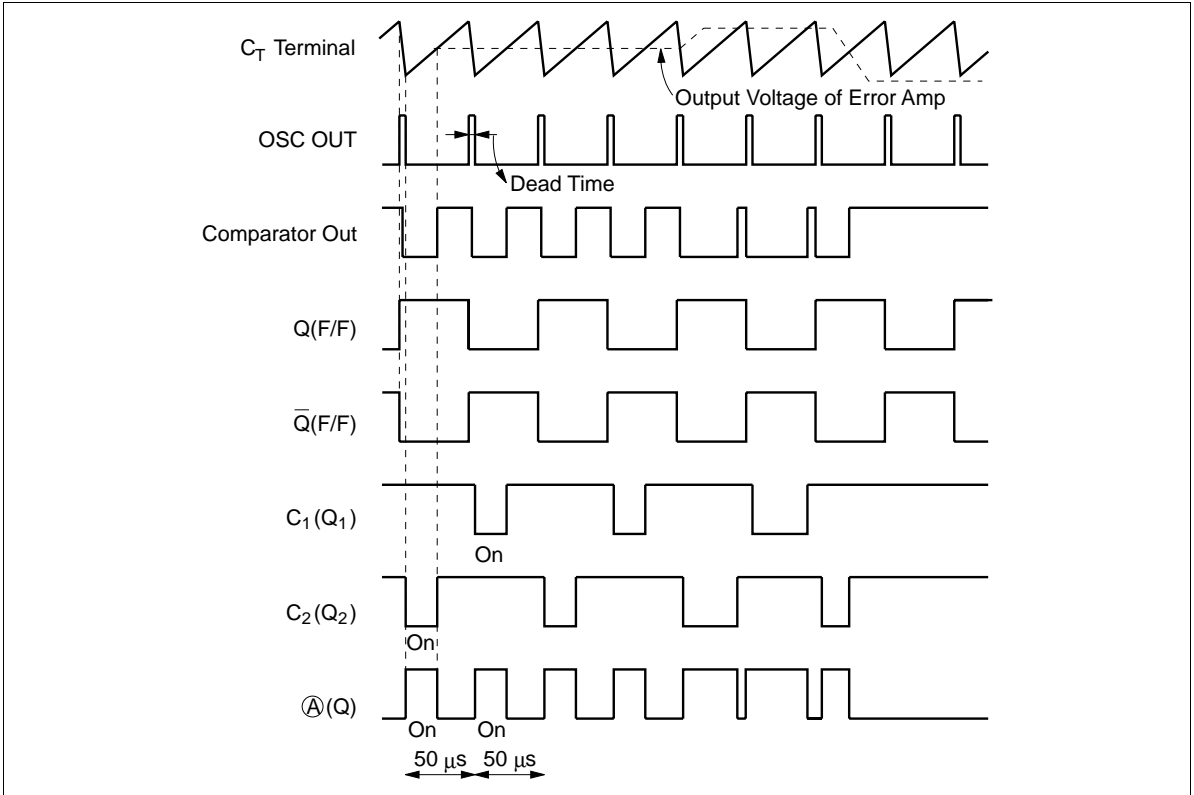
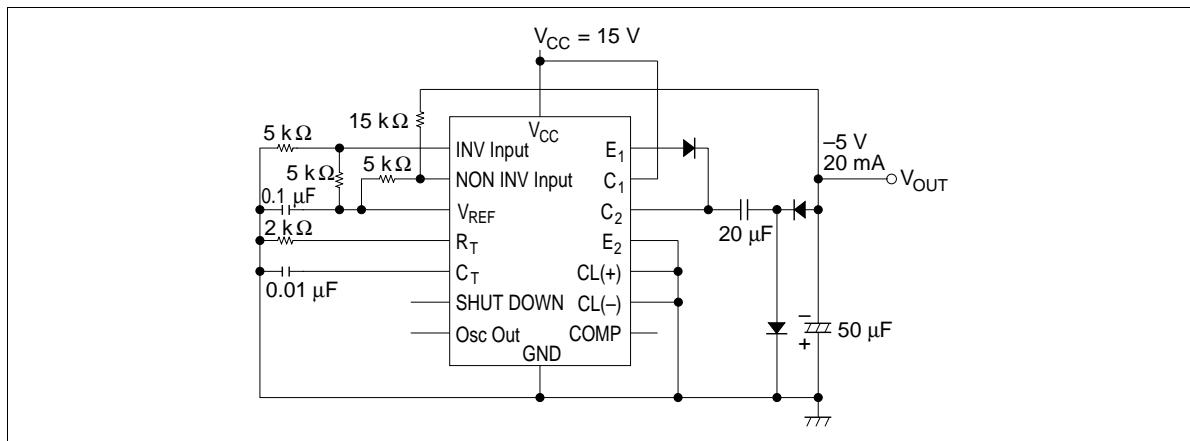


Figure 9 Operating Waveforms



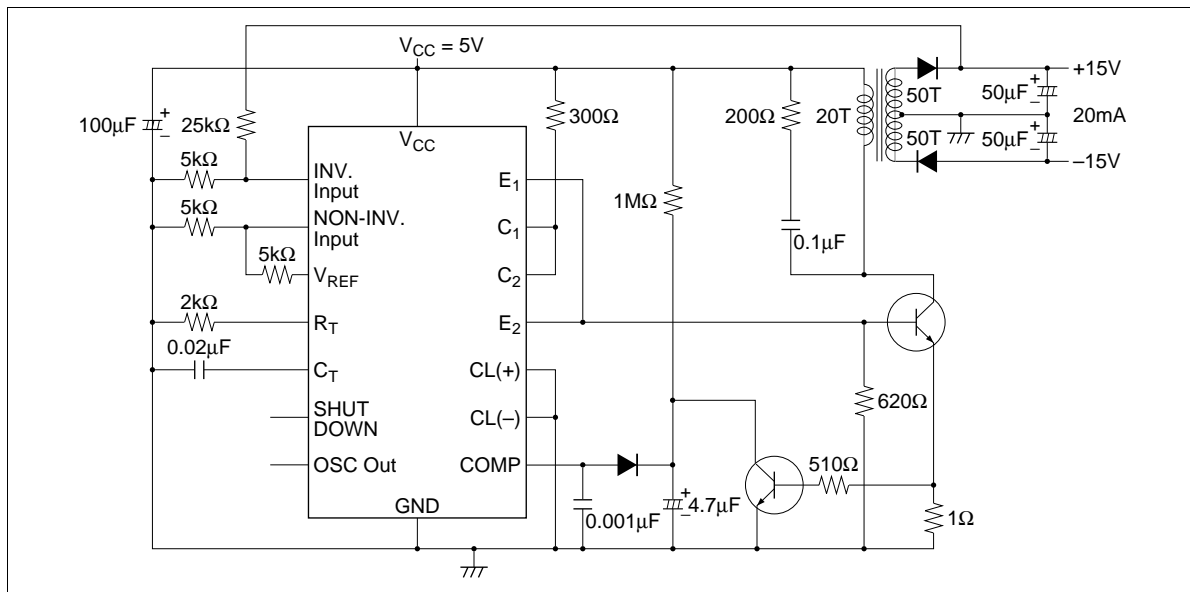
**Circuit Applications**

Simplified inverting Regulator: Figure 10 shows the circuit configuration of HA17524 inverting regulator for light load ( $V_{OUT} = -5\text{ V}$ )



**Figure 10 Simple Polarity Conversion**

Tracking Switching Regulator: Figure 11 shows the circuit configuration of a tracking regulator that uses a transformer. ( $V_{OUT} = \pm 15\text{ V}$ )



**Figure 11 Tracking Switching Regulator**

Push Pull Switching Regulator: Figure 12 shows the circuit configuration of push-pull switching regulator that uses transformer. This system is suited for high power. Output transistors inside HA17524 can drive external switching transistors.

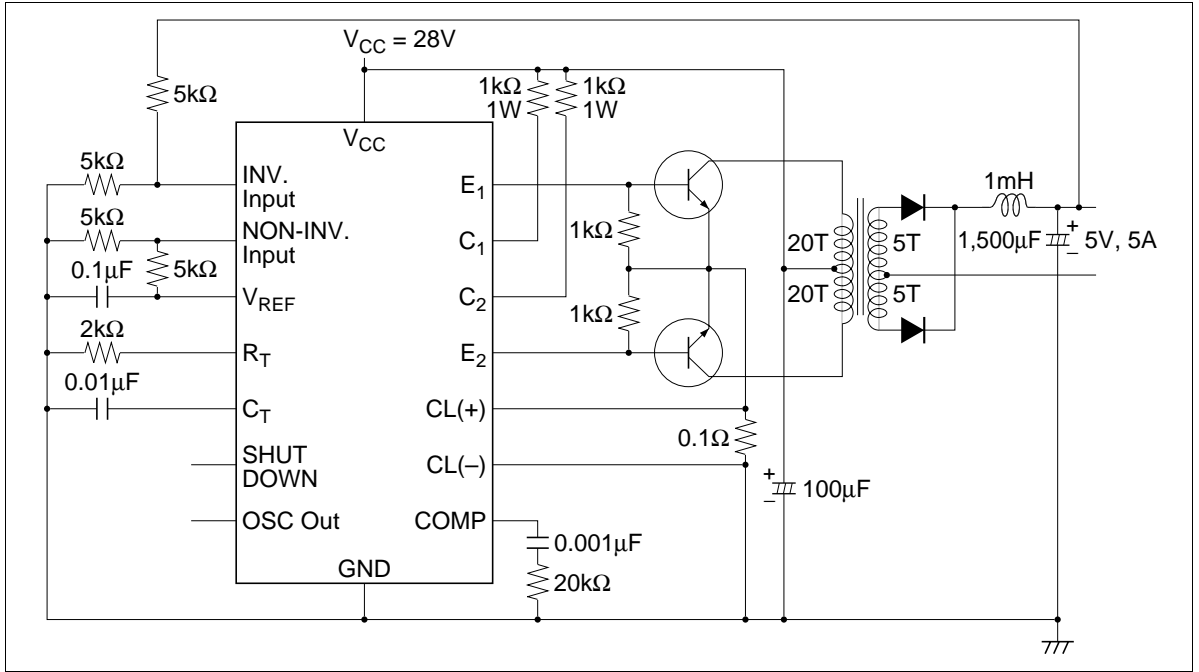


Figure 12 Push-Pull Switching Regulator

## Note

Compared with conventional series regulators, switching regulators generate high frequency noise by switching current quickly. To reduce noise

1. As a general rule, insert line filter to reduce noise at the input.
2. To reduce noise at the output:
  - a. Twist output wiring together.
  - b. Do not bundle power source and output wiring.
  - c. Insert capacitor should be inserted at the load side.
  - d. Ground the power frame.
3. When choosing external parts (external switching transistor, diode, coil, etc) consider their capacitance and characteristics.

**Absolute Maximum Ratings** (Unless otherwise specified,  $T_a = +25^\circ\text{C}$ )

| Item                                 | Symbol    | Rating      | Unit             | Note |
|--------------------------------------|-----------|-------------|------------------|------|
| Supply voltage                       | $V_{CC}$  | 40          | V                | 1, 2 |
| Collector output current             | $I_C$     | 100         | mA               |      |
| Reference output current             | $I_{REF}$ | 50          | mA               |      |
| Current through $C_T$ terminal       | $I_{CT}$  | 5           | mA               |      |
| Continuous total power dissipation   | $P_T$     | 600         | mW               | 3    |
| Operating free-air temperature range | $T_{opr}$ | -20 to +75  | $^\circ\text{C}$ |      |
| Storage temperature range            | $T_{stg}$ | -55 to +125 | $^\circ\text{C}$ |      |

Notes: 1. With respect to network ground terminal

2. The reference voltage can be given by connecting the  $V_{CC}$  and 5 V reference output pins both to the supply voltage. In this configuration,  $V_{CC} = 6\text{ V}$  max.

3. HA17524P: Value at  $T_a \leq 52.7^\circ\text{C}$ , If  $T_a > 52.7^\circ\text{C}$ , derate by  $8.3\text{ mW}/^\circ\text{C}$

## Electrical Characteristics ( $V_{CC} = 20\text{ V}$ , $f = 20\text{ kHz}$ , $T_a = 25^\circ\text{C}$ )

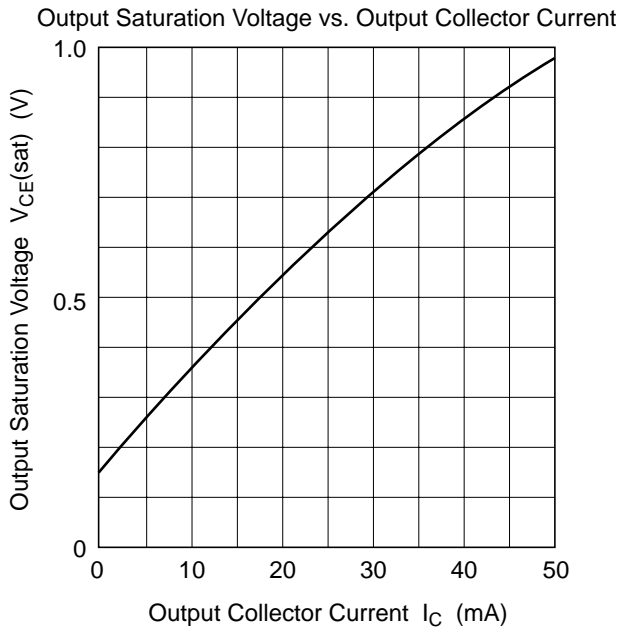
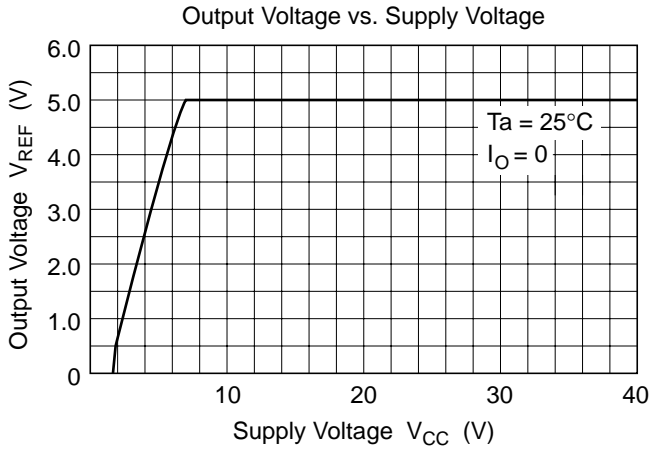
| Item                                |   | Symbol                    | Min        | Typ | Max           | Unit                              | Test Conditions   |
|-------------------------------------|---|---------------------------|------------|-----|---------------|-----------------------------------|---|
| Regulator                           | Output voltage                                | $V_{REF}$                 | 4.6        | 5.0 | 5.4           | V                                 |   |
|                                     | Input regulation                              | $\delta V_{OLine}$        | —          | 10  | 30            | mV                                | $V_{CC} = 8\text{ to }40\text{ V}$  |
|                                     | Ripple rejection                              | $R_{REJ}$                 | —          | 66  | —             | dB                                | $f = 120\text{ Hz}$   |
|                                     | Output regulation                             | $\delta V_{OLoad}$        | —          | 20  | 50            | mV                                | $I_{out} = 0\text{ to }20\text{ mA}$  |
|                                     | Output voltage change with output temperature | $\delta V_O / \delta T_a$ | —          | 0.3 | 1.0           | %                                 | $T_a = 0\text{ to }+70^\circ\text{C}$   |
|                                     |   |                           | —          | 0.4 | 1.36          | %                                 | $T_a = -20\text{ to }+75^\circ\text{C}$   |
| Short-circuit output current (Note) | $I_{OS}$                                      | —                         | 100        | —   | mA            | $V_{REF} = 0$                     |   |
| Error amplifier                     | Input offset voltage                          | $V_{IO}$                  | —          | 2   | 10            | mV                                | $V_{IC} = 2.5\text{ V}$   |
|                                     | Input bias current                            | $I_I$                     | —          | 2   | 10            | $\mu\text{A}$                     | $V_{IC} = 2.5\text{ V}$   |
|                                     | Open-loop voltage gain                        | $A_{VD}$                  | —          | 60  | —             | dB                                |   |
|                                     | Common-mode input voltage range               | $V_{CM}$                  | 1.8 to 3.4 | —   | —             | V                                 | $T_a = 25^\circ\text{C}$  |
|                                     | Common-mode Rejection ratio                   | CMR                       | —          | 70  | —             | dB                                |   |
|                                     | Unity-gain bandwidth                          | BW                        | —          | 3   | —             | MHz                               |   |
|                                     | Output swing                                  | $V_{OPP}$                 | 0.5        | —   | 3.8           | V                                 |   |
| Oscillator                          | OSC frequency                                 | $f$                       | —          | 450 | —             | kHz                               | $C_T = 0.001\ \mu\text{F}$ ,<br>$R_T = 2\ \text{k}\Omega$   |
|                                     | Standard deviation of frequency               | $\Delta f$                | —          | 5   | —             | %                                 | $V_{CC} = 8\text{ to }40\text{ V}$ ,<br>$R_T = 1.8\text{ to }100\ \text{k}\Omega$ ,<br>$C = \text{Const}$ |
|                                     | Frequency stability                           | $\delta f_{Line}$         | —          | —   | 1.0           | %                                 | $V_{CC} = 8\text{ to }40\text{ V}$  |
|                                     |   |                           | —          | 5.0 | 10            | %                                 | $T_a = 0\text{ to }+70^\circ\text{C}$   |
|                                     |   |                           | —          | 5.0 | 13.6          | %                                 | $T_a = -20\text{ to }+75^\circ\text{C}$   |
| Output amplitude                    | $V_{3(\text{peak})}$                          | —                         | 3.5        | —   | V             | Pin 3                             |   |
| Output pulse width                  | $T_P$   | —                         | 0.5        | —   | $\mu\text{s}$ | $C_T = 0.01\ \mu\text{F}$ , Pin 3 |   |
| Comparator                          | Maximum duty cycle                            | Dmax                      | 45         | —   | —             | %                                 |   |
|                                     | Threshold voltage                             | $V_{th\ 0}$               | —          | 1.0 | —             | V                                 | Duty cycle = 0  |
|                                     |   | $V_{th\ max}$             | —          | 3.5 | —             | V                                 | Duty cycle = max  |
| Input bias current                  | $I_I$   | —                         | -1         | —   | $\mu\text{A}$ |                                   |   |

Note: Duration of the short-circuit should not exceed one second.

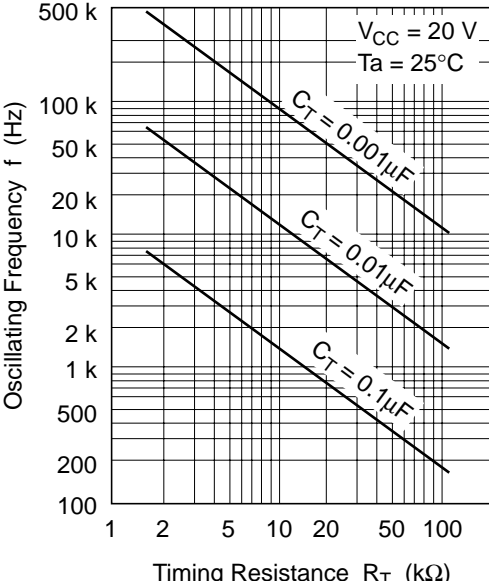
**Electrical Characteristics** ( $V_{CC} = 20\text{ V}$ ,  $f = 20\text{ kHz}$ ,  $T_a = 25^\circ\text{C}$ ) (cont)

| Item            |                                      | Symbol                  | Min          | Typ  | Max | Unit          | Test Conditions  |
|-----------------|--------------------------------------|-------------------------|--------------|------|-----|---------------|--|
| Current limiter | Input voltage range                  | $V_{IS}$                | -0.7 to +1.0 | —    | —   | V             |  |
|                 | Sense voltage                        | $V_S$                   | 180          | 200  | 220 | mV            | $V(\text{Pin } 9) = 2\text{ V}$ ,<br>$T_a = 25^\circ\text{C}$<br>$V(\text{Pin } 2)$<br>$-V(\text{Pin } 1) \geq 50\text{ mV}$ |
|                 | Sensevoltage change with temperature | $\delta V_S/\delta T_a$ | —            | 0.2  | —   | mV/°C         | $T_a = -20\text{ to }+75^\circ\text{C}$  |
| Output          | Collector-emitter breakdown voltage  | $V_{CE}$                | 40           | —    | —   | V             |  |
|                 | Collector off-state current          | $I_{Leak}$              | —            | 0.01 | 50  | $\mu\text{A}$ | $V_{CE} = 40\text{ V}$   |
|                 | Collector-emitter saturation voltage | $V_{CE(sat)}$           | —            | 1    | 2   | V             | $I_C = 50\text{ mA}$   |
|                 | Emitter output voltage               | $V_E$                   | 17           | 18   | —   | V             | $V_{CC} = 20\text{ V}$ ,<br>$I_E = -250\text{ }\mu\text{A}$  |
|                 | Rise time                            | $t_r$                   | —            | 0.2  | —   | $\mu\text{s}$ | $R_C = 2\text{ k}\Omega$   |
|                 | Fall time                            | $t_f$                   | —            | 0.1  | —   | $\mu\text{s}$ |  |
| Total device    | Standby current                      | $I_{ST}$                | —            | 5.0  | 10  | $\text{mA}$   | $V_{CC} = 40\text{ V}$ , $V_2 = 2\text{ V}$ ,<br>Pins 1, 4, 7, 8, 9, 11,<br>14 grounded,<br>All other pins open              |

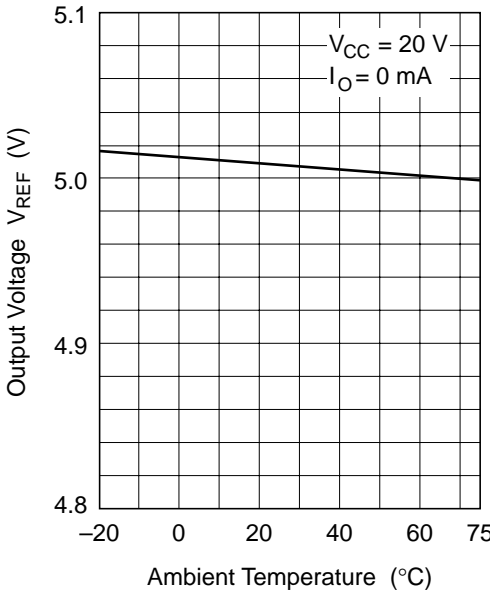
## Characteristic Curves

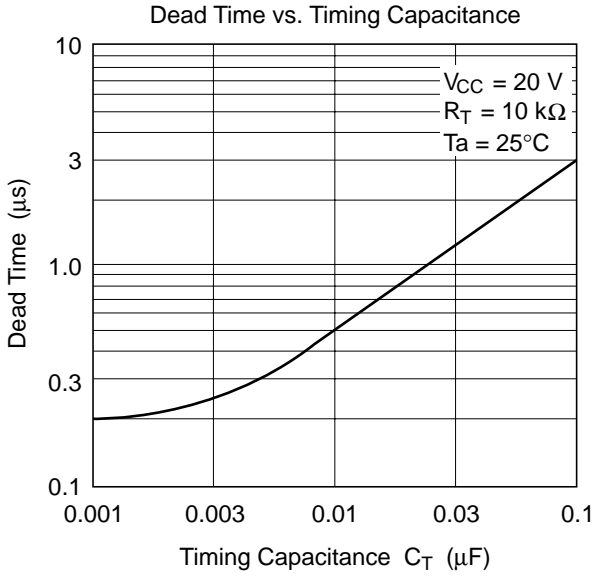


Oscillating Frequency vs. Timing Resistance



Output Voltage vs. Ambient Temperature

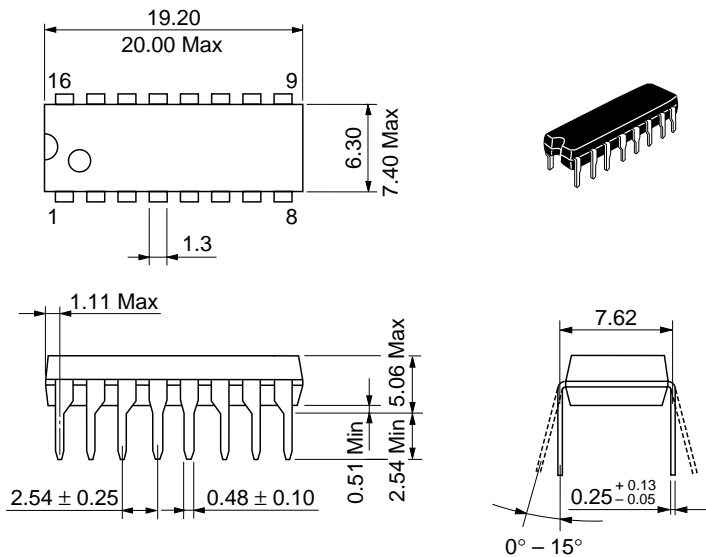






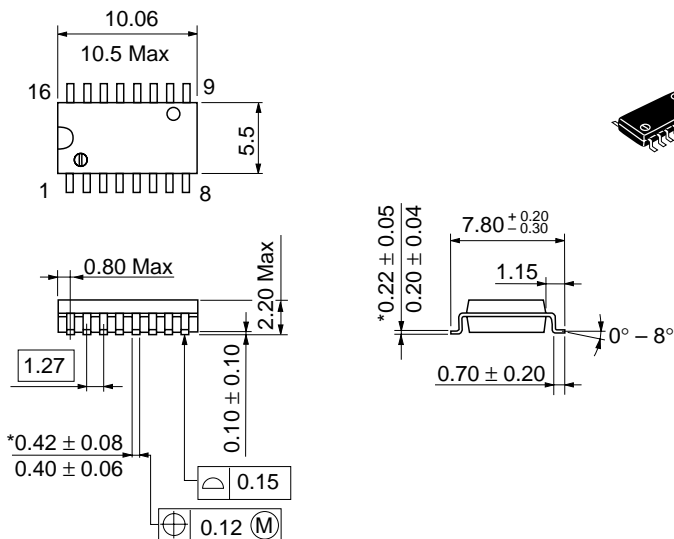
Package Dimensions

Unit: mm



|                        |          |
|------------------------|----------|
| Hitachi Code           | DP-16    |
| JEDEC                  | Conforms |
| EIAJ                   | Conforms |
| Mass (reference value) | 1.07 g   |

Unit: mm



|                        |          |
|------------------------|----------|
| Hitachi Code           | FP-16DA  |
| JEDEC                  | —        |
| EIAJ                   | Conforms |
| Mass (reference value) | 0.24 g   |

\*Dimension including the plating thickness  
Base material dimension

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